

**SOME THRESHOLD THEOREMS OF A TWO-SPECIES  
COMPETING ECOLOGICAL MODEL**

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**ABSTRACT**

In the present investigation the stability analysis of a two-species competing ecological model is highlighted in view of principle of competitive exclusion due to Gause (1934). The model is characterised by a pair of non-linear system of ordinary differential equations. The four equilibrium states are identified and a threshold theorem is derived to establish the stability of the co-existent equilibrium state.

**KEY WORDS:** Competitive exclusion, Threshold results, Stability, Equilibrium states

**AMS CLASSIFICATION:** 92 D 25, 92 D 40

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**1. Basic Equations**

The model equations for a two species ( $S_1$  &  $S_2$ ) competing system is given by the system of following couple of non-linear ordinary differential equations employing the following notations.

$$\frac{dN_1}{dt} = a_1 N_1 - a_{11} N_1^2 - a_{12} N_1 N_2 \quad (1.1)$$

$$\frac{dN_2}{dt} = a_2 N_2 - a_{22} N_2^2 - a_{21} N_1 N_2 \quad (1.2)$$

$N_1, N_2$  : Population sizes of species  $S_1$  &  $S_2$  respectively at time 't'

$a_1, a_2$  : Natural growth rates

$a_{11}, a_{22}$  : Rates of decrease of species due to limitation of natural resources

$a_{12}, a_{21}$  : Inhibition coefficients (Rates of decrease of each because of inhibition of other)

All these coefficients  $a_1, a_2, a_{11}, a_{22}, a_{12}, a_{21} > 0$

## 2. Equilibrium States

Under the conditions,  $\frac{dN_1}{dt} = 0, \frac{dN_2}{dt} = 0$  (2.1)

The competing system under investigation has four equilibrium states. They are

I.  $\bar{N}_1 = 0, \bar{N}_2 = 0$  (Fully washed out state) (2.2)

II.  $\bar{N}_1 = 0, \bar{N}_2 = \frac{a_2}{a_{22}}$  ( $S_1$  washed out state) (2.3)

III.  $\bar{N}_1 = \frac{a_1}{a_{11}}, \bar{N}_2 = 0$  ( $S_2$  washed out state) (2.4)

IV.  $\bar{N}_1 = \frac{a_1 a_{22} - a_2 a_{12}}{a_{11} a_{22} - a_{12} a_{21}}; \bar{N}_2 = \frac{a_2 a_{11} - a_1 a_{21}}{a_{11} a_{22} - a_{12} a_{21}}$  (Co-existent state) (2.5)

This is possible when  $\frac{a_{12}}{a_{22}} < \frac{a_1}{a_2} < \frac{a_{11}}{a_{21}}$  (2.6)

The co-existent state where both species would exist is also known as "Normal steady state".

### 3. Threshold Theorems

#### Principle of competitive exclusion (Gauss (1934)).

**“Two species cannot indefinitely co-exist in the same locality if they have identical ecological requirements”**

In consonance with the above principle we derive a Threshold Theorem for the co-existent equilibrium state. We write the basic equations as

$$\frac{dN_1}{dt} = \frac{a_1 N_1}{k_1} \{k_1 - N_1 - \beta_1 N_2\}, \quad \frac{dN_2}{dt} = \frac{a_2 N_2}{k_2} \{k_2 - N_2 - \beta_2 N_1\} \quad (3.1)$$

where

$$k_1 = \frac{a_1}{a_{11}}, \quad k_2 = \frac{a_2}{a_{22}}, \quad \beta_1 = \frac{a_{12}}{a_{11}}, \quad \beta_2 = \frac{a_{21}}{a_{22}}$$

#### Theorem 1: Principle of Competitive Exclusion for Equilibrium State IV:

$$\bar{N}_1 = \frac{a_1 a_{22} - a_2 a_{12}}{a_{11} a_{22} - a_{12} a_{21}}; \quad \bar{N}_2 = \frac{a_2 a_{11} - a_1 a_{21}}{a_{11} a_{22} - a_{12} a_{21}}$$

When  $\frac{k_1}{\beta_1} > k_2$  and  $\frac{k_2}{\beta_2} > k_1$  then every solution  $(N_1(t), N_2(t))$  of (3.1) approaches the

equilibrium solution  $N_1(t) = \bar{N}_1 (\neq 0)$  and  $N_2(t) = \bar{N}_2 (\neq 0)$  as  $t$  approaches infinity. In other words if species 1 and 2 are nearly identical and the microcosm can support both the members of species 1 and 2 depending up on the initial conditions.

**Proof:** The first step in our proof is to show that  $N_1(t)$  and  $N_2(t)$  can never become negative. To this end, observe that

$$N_1(t) = \bar{N}_1 = \frac{a_1 a_{22} - a_2 a_{12}}{a_{11} a_{22} - a_{12} a_{21}}; \quad N_2(t) = \bar{N}_2 = \frac{a_2 a_{11} - a_1 a_{21}}{a_{11} a_{22} - a_{12} a_{21}}$$

Is a solution of (3.1) for any Choice of  $N_1(t)$ . The orbit of this solution in the  $N_1$ - $N_2$  plane is the point  $(0,0)$  for  $N_1(t)=0, N_2=0$  : the line  $0 < N_1 < k_1, N_2=0$  for  $0 < N_1(t) < k_1$ ; the point  $(k_1,0)$  for  $N_1(t)=k_1$ ;

And the line  $k_1 < N_1 < \infty, N_2 = 0$  for  $N_1(t) > k$ . thus the  $N_1$  axis, for  $N_1 \geq 0$  is the union of four distinct orbits of (3.1). Similarly the  $N_2$  axis, for  $N_2 \geq 0$  is the union of four distinct orbits of (3.1). thus implies that all solutions  $(N_1(t), N_2(t))$  of (3.1) which start in the first quadrant ( $N_1(t) > 0, N_2(t) > 0$ ) of the  $N_1$ - $N_2$  plane must remain there for all future time.

The second step in our proof is to split the first quadrant into regions in which both  $\frac{dN_1}{dt}$  and  $\frac{dN_2}{dt}$  have fixed signs. This is accomplished in the following manner.

Let  $l_1$  and  $l_2$  be the lines  $k_1 - N_1 - \beta_1 N_2 = 0$  and  $k_2 - N_2 - \beta_2 N_1 = 0$ , respectively and the point of their intersection is  $(\bar{N}_1, \bar{N}_2)$ . Observe that  $\frac{dN_1}{dt}$  is negative if  $(N_1, N_2)$  lies above the line  $l_1$  and positive if  $(N_1, N_2)$  lies below  $l_1$ . Similarly  $\frac{dN_2}{dt}$  is negative if  $(N_1, N_2)$  lies above  $l_2$  and positive if  $(N_1, N_2)$  lies below  $l_2$  thus the two lines  $l_1$  and  $l_2$  split the first quadrant of the  $N_1$ - $N_2$  plane into four regions in which both  $\frac{dN_1}{dt}$  and  $\frac{dN_2}{dt}$  have fixed signs.

$N_1(t), N_2(t)$  both increase with time (along any solution of (3.1) in region I;

$N_1(t)$  increases and  $N_2(t)$  decreases with time in region II;

$N_1(t)$  decreases and  $N_2(t)$  increases with time in region III;

And both  $N_1(t)$  and  $N_2(t)$  decreases with time in region IV. in this region both the  $S_1$  and  $S_2$  complete with each other but do not flourish and at the same time do not get extinct as shown in Fig 1.1

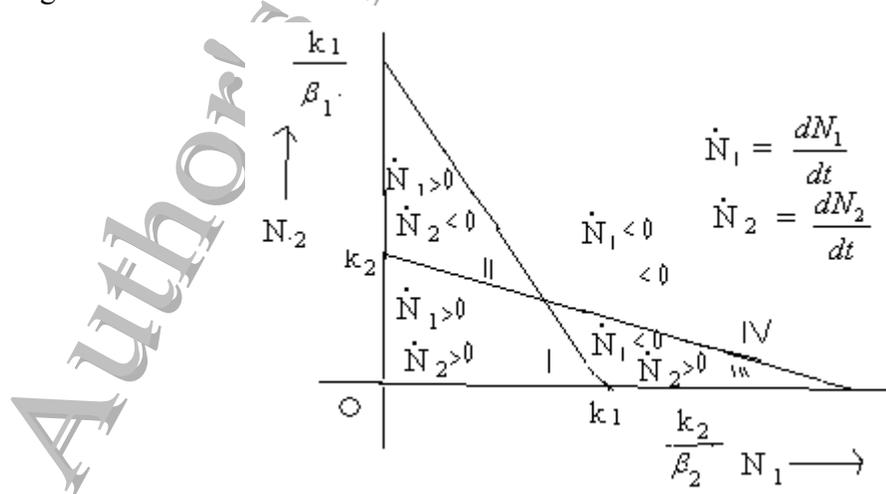


Fig.1.1

Finally we require the following four lemmas.

**Lemma 1:** Any Solution  $(N_1(t), N_2(t))$  of (3.1) which starts in region I at time  $t=t_0$  will remain in this region for all future  $t \geq t_0$ , and ultimately approach the equilibrium

solution  $N_1(t) = \bar{N}_1, N_2(t) = \bar{N}_2$  (Fig.1.2).

**Proof:** Suppose that a solution  $(N_1(t), N_2(t))$  of (3.1) leaves region at time  $t=t^*$ . Then

either  $\frac{dN_1(t^*)}{dt}$  or  $\frac{dN_2(t^*)}{dt}$  is zero, since the only way a solution of (3.1) can leave region

is by crossing  $I_1$  or  $I_2$ . Assume that  $\frac{dN_1(t^*)}{dt} = 0$ . Differentiating both sides of the first

equation of (3.1) with respect to  $t$  and setting  $t=t^*$  gives

$$\frac{d^2 N_1(t^*)}{dt^2} = \frac{-a_1 \beta_1 N_1(t^*)}{k_1} \frac{dN_2(t^*)}{dt} < 0 \quad (3.2)$$

Hence  $N_1(t)$  is monotonic increasing and it has maximum whenever a solution of  $N_1(t), N_2(t)$  of (3.1) is in region I.

Similarly, if  $\frac{dN_2(t^*)}{dt} = 0$

Then

$$\frac{d^2 N_2(t^*)}{dt^2} = \frac{-a_2 \beta_2 N_2(t^*)}{k_2} \frac{dN_1(t^*)}{dt} < 0 \quad (3.3)$$

implies that  $N_2(t)$  is monotonic increasing and it has maximum whenever a solution  $N_1(t), N_2(t)$  of (3.1) is in region I.

If a solution  $(N_1(t), N_2(t))$  of (3.1) remains in region I for  $t \geq t_0$ , then both  $N_1(t)$  and  $N_2(t)$  are monotonic increasing functions of time for  $t \geq t_0$ , with  $N_1(t) < k_1$  and  $N_2(t) < k_2$ ,

consequently, both  $N_1(t)$  and  $N_2(t)$  have limits  $\xi, \eta$  respectively, as  $t$  approaches infinity.

This, in turn implies that  $(\xi, \eta)$  is an equilibrium point of (3.1). Now,  $(\xi, \eta)$  obviously

cannot equal  $(0, 0)$   $(k_1, 0)$  or  $(0, k_2)$  consequently  $(\xi, \eta) = (\bar{N}_1, \bar{N}_2)$ .

**Lemma 2:** Any solution of  $(N_1(t), N_2(t))$  of (3.1) which starts in region II at time  $t=t_0$  will remain in this region for all future time  $t \geq t_0$  and ultimately approach the equilibrium solution  $N_1(t) = \bar{N}_1, N_2(t) = \bar{N}_2$  (Fig.1.2).

**Proof:** Suppose that a solution  $(N_1(t), N_2(t))$  of (3.1) leaves region II at time  $t=t^*$ . Then

either  $\frac{dN_1(t^*)}{dt}$  or  $\frac{dN_2(t^*)}{dt}$  is zero, since the only way a solution of (3.1) can leave region

II is by crossing  $I_1$  or  $I_2$ . Assume that  $\frac{dN_1(t^*)}{dt} = 0$ . Differentiating both sides of the first equation of (3.1) with respect to  $t$  and setting  $t=t^*$  gives

$$\frac{d^2 N_1(t^*)}{dt^2} = \frac{-a_1 \beta_1 N_1(t^*)}{k_1} \frac{dN_2(t^*)}{dt} \quad (3.4)$$

This quantity is positive. Hence  $N_1(t)$  has a minimum at  $t=t^*$ . However this is impossible, since  $N_1(t)$  is increasing whenever a solution of  $(N_1(t), N_2(t))$  of (3.1) is in region II.

Similarly, if  $\frac{dN_2(t^*)}{dt} = 0$ ,

Then

$$\frac{d^2 N_2(t^*)}{dt^2} = \frac{-a_2 \beta_2 N_2(t^*)}{k_2} \frac{dN_1(t^*)}{dt} \quad (3.5)$$

This quantity is negative. Hence  $N_2(t)$  has a maximum at  $t=t^*$ . However this is impossible, since  $N_2(t)$  is decreasing whenever a solution of  $(N_1(t), N_2(t))$  of (3.1) is in region II.

The previous argument shows that any solution  $(N_1(t), N_2(t))$  of (3.1) which starts in region II at time  $t=t_0$  will remain in region II for all future time  $t \geq t_0$ . This implies that

$N_1(t)$  is monotonic increasing and  $N_2(t)$  is monotonic decreasing for  $t \geq t_0$  with  $N_1(t) < k_1$  and  $N_2(t) > k_2$ . Consequently both  $N_1(t)$  and  $N_2(t)$  have limits  $\xi, \eta$  respectively as  $t$  approaches infinity. This in turn implies that  $(\xi, \eta)$  is an equilibrium point of (3.1). Now

obviously cannot equal  $(0, 0)$   $(k_1, 0)$  or  $(0, k_2)$ . Consequently  $(\xi, \eta) = (\bar{N}_1, \bar{N}_2)$  and this proves Lemma 2.

**Lemma 3:** Any solution  $(N_1(t), N_2(t))$  of (3.1) which starts in region III at time  $t=t_0$  will remain in this region for all future time  $t \geq t_0$ , and ultimately approach the equilibrium solution  $N_1(t) = \overline{N}_1, N_2(t) = \overline{N}_2$  (Fig.1.2).

**Proof:** Suppose that a solution  $(N_1(t), N_2(t))$  of (3.1) leaves region III at time  $t=t^*$ , then

either  $\frac{dN_1(t^*)}{dt}$  or  $\frac{dN_2(t^*)}{dt}$  is zero. Since the only way a solution of (3.1) can leave region

III is by crossing  $I_1$  or  $I_2$ . Assume that  $\frac{dN_1(t^*)}{dt} = 0$ . Differentiating both sides of the first equation of (3.1) with respect to  $t$  and setting  $t=t^*$  gives

$$\frac{d^2 N_1(t^*)}{dt^2} = \frac{-a_1 \beta_1 N_1(t^*)}{k_1} \frac{dN_2(t^*)}{dt} \quad (3.6)$$

This quantity is negative. Hence  $N_1(t)$  has a maximum at  $t=t^*$ . However this is impossible since  $N_1(t)$  is decreasing whenever a solution of  $(N_1(t), N_2(t))$  of (3.1) is in region III.

Similarly, if  $\frac{dN_2(t^*)}{dt} = 0$ ,

Then

$$\frac{d^2 N_2(t^*)}{dt^2} = \frac{-a_2 \beta_2 N_2(t^*)}{k_2} \frac{dN_1(t^*)}{dt} \quad (3.7)$$

This quantity is positive. Hence  $N_2(t)$  has a minimum at  $t=t^*$ . However this is impossible since  $N_2(t)$  is increasing whenever a solution of  $(N_1(t), N_2(t))$  of (3.1) is in region III.

The previous argument shows that any solution  $(N_1(t), N_2(t))$  of (3.1) which starts in region III at time  $t=t_0$  will remain in region III for all future time  $t \geq t_0$ . This implies that  $N_1(t)$  is monotonic increasing  $N_2(t)$  is monotonic decreasing for  $t \geq t_0$  with  $N_1(t) > k_1$  and  $N_2(t) < k_2$ . Consequently both  $N_1(t)$  and  $N_2(t)$  have limits  $\xi, \eta$  respectively as  $t$  approaches infinity. This in turn implies that  $(\xi, \eta)$  is an equilibrium point of (3.1). Now  $(\xi, \eta)$  obviously cannot equal  $(0, 0)$   $(k_1, 0)$  or  $(0, k_2)$ . Consequently  $(\xi, \eta) = (\overline{N}_1, \overline{N}_2)$  and this proves Lemma 3.

**Lemma 4:** Any solution of  $(N_1(t), N_2(t))$  of (3.1) which starts in region IV at time  $t$  will remain in this region for all future time  $t \geq t_0$  and ultimately approach the equilibrium

solution  $N_1(t) = \overline{N}_1, N_2(t) = \overline{N}_2$  (Fig.1.2)

**Proof:** Suppose that a solution  $(N_1(t), N_2(t))$  of (3.1) leaves region IV at time  $t=t^*$ . Then

either  $\frac{dN_1(t^*)}{dt}$  or  $\frac{dN_2(t^*)}{dt}$  is zero. Since the only way a solution of (3.1) and leave region

IV is by crossing  $I_1$  or  $I_2$ . Assume that  $\frac{dN_1(t^*)}{dt} = 0$ . Differentiating both sides of the first equation of (3.1) with respect to  $t$  and setting  $t=t^*$  gives

$$\frac{d^2 N_1(t^*)}{dt^2} = \frac{-a_1 \beta_1 N_1(t^*)}{k_1} \frac{dN_2(t^*)}{dt} \quad (3.8)$$

This quantity is positive. Hence  $N_1(t)$  is monotonically decreasing and it has minimum whenever a solution  $(N_1(t), N_2(t))$  of (3.1) is in region IV.

Similarly, if  $\frac{dN_2(t^*)}{dt} = 0$ ,

Then

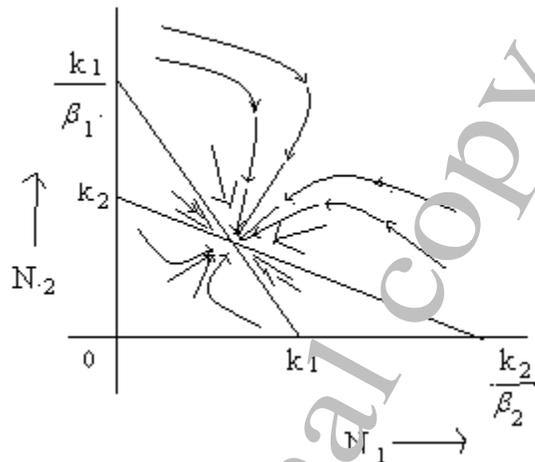
$$\frac{d^2 N_2(t^*)}{dt^2} = \frac{-a_2 \beta_2 N_2(t^*)}{k_2} \frac{dN_1(t^*)}{dt} \quad (3.9)$$

This quantity is positive, implying that  $N_2(t)$  is monotonically decreasing and it has minimum whenever a solution  $(N_1(t), N_2(t))$  of (3.1) is in region IV.

If a solution  $(N_1(t), N_2(t))$  of (3.1) remains in region IV for  $t \geq t_0$ , the both  $N_1(t)$  and  $N_2(t)$  are monotonic decreasing functions of time for  $t \geq t_0$ , with  $N_1(t) > k_1$  and  $N_2(t) > k_2$ , consequently, both  $N_1(t)$  and  $N_2(t)$  have limits  $\xi, \eta$  respectively, as  $t$  approaches infinity. This, in turn implies that  $(\xi, \eta)$  is an equilibrium point of (3.1). Now, obviously  $(\xi, \eta)$  cannot equal  $(0, 0)$  ( $k_1, 0$ ) or  $(0, k_2)$ . Consequently,  $(\xi, \eta) = (\overline{N}_1, \overline{N}_2)$

**Proof of Theorem 1:** Lemmas 1,2,3 and 4 state that every solution  $(N_1(t), N_2(t))$  of (3.1) which starts in region I, II, III or IV at time  $t=t_0$  and remains there for future time must also approach equilibrium solution  $N_1(t) = \overline{N}_1, N_2(t) = \overline{N}_2$  as  $t$  approaches infinity. Next,

observe that any solution  $(N_1(t), N_2(t))$  of (3.1) which starts on  $I_1$  and  $I_2$  must immediately afterwards enter regions I, II, III or IV. Finally the solution approaches the equilibrium solution  $N_1(t) = \bar{N}_1, N_2(t) = \bar{N}_2$ . This is illustrated in Fig.1.2



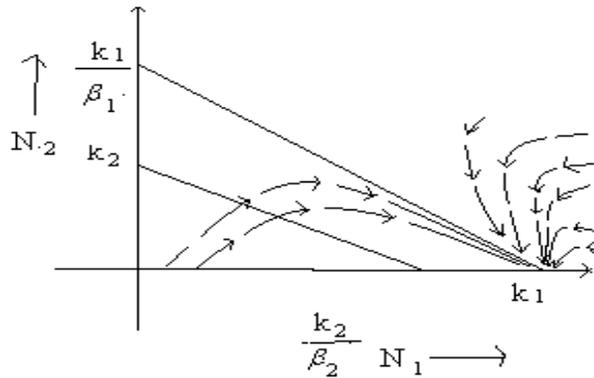
**Fig.1.2**

**In the similar lines as above two more threshold theorems ,one for each of the non-washedout equilibrium states are deduced below.**

**Theorem 2:** Principle of Competitive Exclusion for Equilibrium State III

$$\bar{N}_1 = \frac{a_1}{a_{11}} : \bar{N}_2 = 0$$

When  $k_1 > k_2$ , then every solution  $(N_1(t), N_2(t))$  of (3.1) approaches the equilibrium solution  $N_1 = k_1, N_2 = 0$  as  $t$  approaches infinity . In other words, if species 1 and 2 are nearly identical and the microcosm can support more members of species 1 than species 2, then species 2 will ultimately becomes extinct.

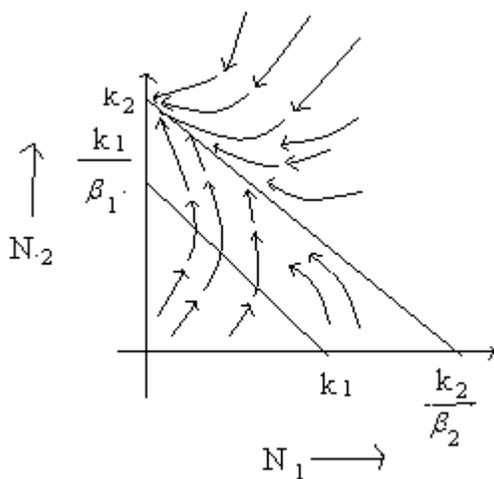


**Fig1.3**

**Theorem 3:** Principle of Competitive Exclusion for Equilibrium State II:

$$\bar{N}_1 = 0 : \bar{N}_2 = \frac{a_2}{a_{22}}$$

When  $k_1 < k_2$ , then every solution  $(N_1(t), N_2(t))$  of (2.8.1) approaches the equilibrium solution  $N_1=0, N_2=k_2$  as  $t$  approaches infinity. In other words, if species 1 and 2 are nearly identical and the microcosm can support more members of species 2 than species 1, then species 1 will ultimately becomes extinct.



**Fig.1.4**

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