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ON THE STABILITY OF A FOUR SPECIES: A PREY-PREDATOR-HOST-COMMENSAL-SYN ECO-SYSTEM-III
(THE CO-EXISTENT STATE)

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ABSTRACT: This paper deals with an investigation on a Four Species Syn-Ecological System **(The Co-existent State)**. The System comprises of a Prey (S_1), a Predator (S_2) that survives upon S_1, two Hosts S_3 and S_4 for which S_1, S_2 are commensal respectively i.e., S_3 and S_4 benefit S_1 and S_2 respectively, without getting effected either positively or adversely. Further S_3 and S_4 are neutral. The model equations of the system constitute a set of four first order non-linear ordinary differential coupled equations. In all, there are sixteen equilibrium points. Criteria for the asymptotic stability of one of the sixteen equilibrium points : The Co-existent State only is established in this paper. The Co-existent State is found to be conditionally stable. The linearized equations for the perturbations over the equilibrium points are analyzed to establish the criteria for stability and the trajectories illustrated.

1. INTRODUCTION:

Mathematical modeling of Eco-System was initiated in 1925 by Lotka [10] and in 1931 by Volterra[14]. The general concepts of modeling have been presented in the treatises of Meyer[11], Kushing[7], Kapur J.N. [5,6] and several others. The ecological interactions can be broadly classified as Prey-Predator, Commensalism, Competition, Neutralism, Mutualism and so on. N.C. Srinivas [13] studied competitive eco-systems of two species and three species with limited and unlimited resources. Later Lakshminarayan [8], Lakshminarayan and Pattabhi Ramacharyulu [9] studied Prey Preadtor ecological models with partial cover for the Prey and alternate food for the predator. Recently, Archana Reddy [1] and Bhaskara Rama Sharma [2] investigated diverse problems related to two species competitive systems with time delay, employing analytical and numerical techniques. Further Phani Kumar, Seshagiri Rao and Pattabhi Ramacharyulu [12] studied the stability of a Host-A flourishing commensal species pair with limited resources. The present authors Hari Prasad. B and Pattabhi Ramacharyulu.N.Ch studied the stability of the fully washed out state [3] and Prey and Predator washed out states [4]. Continuation of this criteria for the stability of only the co-existent state of the system is presented in this paper.

Fig.1 shows the Schematic Sketch of the system under investigation.

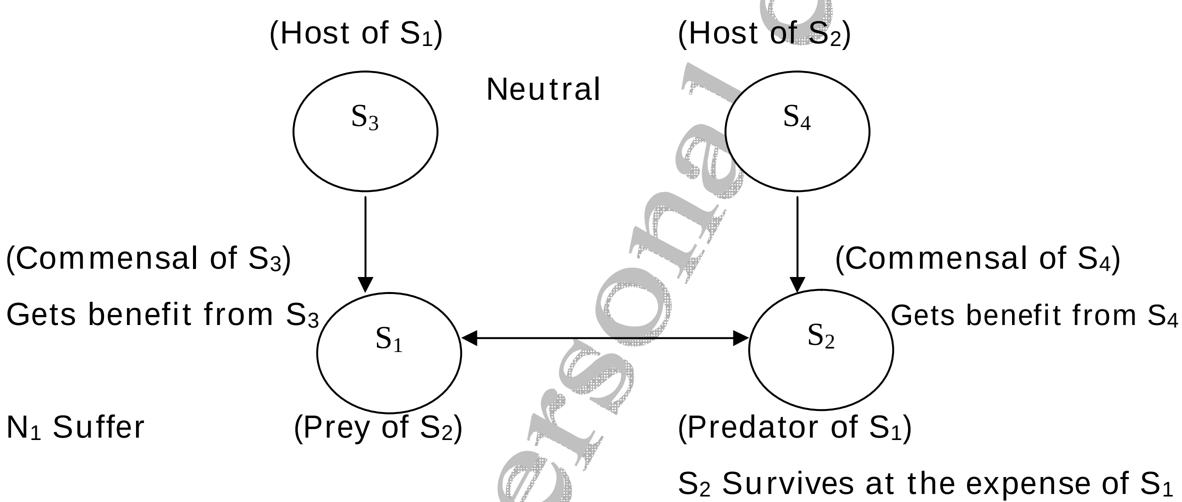


Fig. 1 Schematic Sketch of the Syn Eco - System

2. BASIC EQUATIONS OF THE MODEL:

Notation Adopted:

S_1	:	Prey for S_2 and commensal for S_3.
S_2	:	Predator surviving upon S_1 and commonsal for S_4.
S_3	:	Host for the commonsal - Prey (S_1).
S_4	:	Host of the commonsal - Predator (S_2)
$N_1(t)$	:	The Population of the Prey (S_1)
$N_2(t)$	:	The Population of the Predator (S_2)
$N_3(t)$	:	The Population of the Host (S_3) of the Prey (S_1)
$N_4(t)$	:	The Population of the Host (S_4) of the Predator (S_2)
t	:	Time instant

a_1, a_2, a_3, a_4 : Natural growth rates of S_1, S_2, S_3, S_4

$a_{11}, a_{22}, a_{33}, a_{44}$: Self inhibition coefficients of S_1, S_2, S_3, S_4

a_{12}, a_{21} : Interaction (Prey-Predator) coefficients of S_1 due to S_2 and S_2 due to S_1

a_{13} : Coefficient for commensal for S_1 due to the Host S_3

a_{24} : Coefficient for commensal for S_2 due to the Host S_4

$\frac{a_1}{a_{11}}, \frac{a_2}{a_{22}}, \frac{a_3}{a_{33}}, \frac{a_4}{a_{44}}$: Carrying capacities of S_1, S_2, S_3, S_4

Further the variables N_1, N_2, N_3, N_4 are non-negative and the model parameters a_1, a_2, a_3, a_4; a_{11}, a_{22}, a_{33}, a_{44}; a_{12}, a_{21}, a_{13}, a_{24} are assumed to be non-negative constants.

The model equations for the growth rates of S_1, S_2, S_3, S_4 are

$$\frac{dN_1}{dt} = a_1 N_1 - a_{11} N_1^2 - a_{12} N_1 N_2 + a_{13} N_1 N_3 \qquad \ldots. \quad (2.1)$$

$$\frac{dN_2}{dt} = a_2 N_2 - a_{22} N_2^2 + a_{21} N_1 N_2 + a_{24} N_2 N_4 \qquad \ldots. \quad (2.2)$$

$$\frac{dN_3}{dt} = a_3 N_3 - a_{33} N_3^2 \qquad \ldots. \quad (2.3)$$

$$\frac{dN_4}{dt} = a_4 N_4 - a_{44} N_4^2 \qquad \ldots. \quad (2.4)$$

3 EQUILIBRIUM STATES:

The system under investigation has sixteen equilibrium states defined by

$$\frac{dN_i}{dt} = 0, \; i = 1, 2, 3, 4 \qquad \ldots\ldots\ldots\ldots (3.1)$$

are given in the following table.

S.No.	Equilibrium States	Equilibrium Point
1	Fully Washed out state	$\overline{N_1}=0,\overline{N_2}=0,\overline{N_3}=0,\overline{N_4}=0$
2	Only the Host (S_4)of S_2 survives	$\overline{N_1}=0,\overline{N_2}=0,\overline{N_3}=0,\overline{N_4}=\frac{a_4}{a_{44}}$
3	Only the Host (S_3)of S_1 survives	$\overline{N_1}=0,\overline{N_2}=0,\overline{N_3}=\frac{a_3}{a_{33}},\overline{N_4}=0$
4	Only the Predator S_2 survives	$\overline{N_1}=0,\overline{N_2}=\frac{a_2}{a_{22}},\overline{N_3}=0,\overline{N_4}=0$
5	Only the Prey S_1 survives	$\overline{N_1}=\frac{a_1}{a_{11}},\overline{N_2}=0,\overline{N_3}=0,\overline{N_4}=0$
6	Prey (S_1) and Predator (S_2) washed out	$\overline{N_1}=0,\overline{N_2}=0,\overline{N_3}=\frac{a_3}{a_{33}},\overline{N_4}=\frac{a_4}{a_{44}}$
7	Prey (S_1) and Host (S_3) of S_1 washed out	$\overline{N_1}=0,\overline{N_2}=\frac{a_2a_{44}+a_4a_{24}}{a_{22}a_{44}},\overline{N_3}=0,\overline{N_4}=\frac{a_4}{a_{44}}$
8	Prey (S_1) and Host (S_4) of S_2 washed out	$\overline{N_1}=0,\overline{N_2}=\frac{a_2}{a_{22}},\overline{N_3}=\frac{a_3}{a_{33}},\overline{N_4}=0$
9	Predator (S_2) and Host (S_3) of S_1 washed out	$\overline{N_1}=\frac{a_1}{a_{11}},\overline{N_2}=0,\overline{N_3}=0,\overline{N_4}=\frac{a_4}{a_{44}}$
10	Predator (S_2) and Host (S_4) of S_2 washed out	$\overline{N_1}=\frac{a_1a_{33}+a_3a_{13}}{a_{11}a_{13}},\overline{N_2}=0,\overline{N_3}=\frac{a_3}{a_{33}},\overline{N_4}=0$
11	Prey (S_1) and Predator (S_2)survives	$\overline{N_1}=\frac{a_1a_{22}-a_2a_{12}}{a_{11}a_{22}+a_{12}a_{21}},\overline{N_2}=\frac{a_1a_{21}+a_2a_{11}}{a_{11}a_{22}+a_{12}a_{21}},\overline{N_3}=0,\overline{N_4}=0$
12	Only the Prey (S_1) washed out	$\overline{N_1}=0,\overline{N_2}=\frac{a_2a_{44}+a_4a_{24}}{a_{22}a_{44}},\overline{N_3}=\frac{a_3}{a_{33}},\overline{N_4}=\frac{a_4}{a_{44}}$
13	Only the predator (S_2) washed out	$\overline{N_1}=\frac{a_1a_{23}+a_3a_{13}}{a_{11}a_{13}},\overline{N_2}=0,\overline{N_3}=\frac{a_3}{a_{33}},\overline{N_4}=\frac{a_4}{a_{44}}$

14	Only the Host (S_3) of S_1 washed out	$\overline{N_1} = \frac{\delta_2}{\delta_1}, \overline{N_2} = \frac{\delta_3}{\delta_1}, \overline{N_3} = 0, \overline{N_4} = \frac{a_4}{a_{44}}$ *where* $\delta_1 = a_{44}(a_{11}a_{22} + a_{12}a_{21}) > 0$ $\delta_2 = a_1a_{22}a_{44} - a_{12}(a_2a_{44} + a_4a_{24})$ $\delta_3 = a_1a_{21}a_{44} - a_{11}(a_2a_{44} + a_4a_{24})$
15	Only the Host (S_4) of S_2 washed out	$\overline{N_1} = \frac{\sigma_2}{\sigma_1}, \overline{N_2} = \frac{\sigma_3}{\sigma_1}, \overline{N_3} = \frac{a_3}{a_{33}}, \overline{N_4} = 0$ *where* $\sigma_1 = a_{33}(a_{11}a_{22} + a_{12}a_{21}) > 0$ $\sigma_2 = a_{22}(a_1a_{33} + a_3a_{13}) - a_2a_{12}a_{33}$ $\sigma_3 = a_{21}(a_1a_{33} + a_3a_{13}) + a_2a_{11}a_{33} > 0$
16	The co-existent state (or) Normal steady state	$\overline{N_1} = \frac{a_{22}a_{44}\psi_1 - a_{12}a_{33}\psi_2}{\psi_3}, \overline{N_2} = \frac{a_{21}a_{44}\psi_1 + a_{11}a_{33}\psi_2}{\psi_3},$ $\overline{N_3} = \frac{a_3}{a_{33}}, \overline{N_4} = \frac{a_4}{a_{44}}$ *where* $\psi_1 = a_1a_{33} + a_3a_{13} > 0$ $\psi_2 = a_2a_{44} + a_4a_{24} > 0$ $\psi_3 = a_{33}a_{44}(a_{11}a_{22} + a_{12}a_{21}) > 0$

The present paper deals with the Co-existent State only. The stability of the other equilibrium states will be presented in the forth coming communications.

4. STABILITY OF THE EQUILIBRIUM STATE: The co-existent state (or) Normal steady State: (Sl. No. 16 in the above table)

To discuss the stability of equilibrium point

$$\overline{N}_1 = \frac{a_{22}a_{44}\psi_1 - a_{12}a_{33}\psi_2}{\psi_3}, \overline{N}_2 = \frac{a_{21}a_{44}\psi_1 + a_{11}a_{33}\psi_3}{\psi_3}, \overline{N}_3 = \frac{a_3}{a_{33}}, \overline{N}_4 = \frac{a_4}{a_{44}}$$

where

$$\psi_1 = a_1a_{33} + a_3a_{13} > 0,\ \psi_2 = a_2a_{44} + a_4a_{24} > 0,\ \psi_3 = a_{33}a_{44}\left(a_{11}a_{22} + a_{12}a_{21}\right) > 0 \text{ ------- } (4.1)$$

This would exist only when $a_{22}a_{44}\psi_1 > a_{12}a_{33}\psi_2$ --------- (4.2)

Let us consider small deviations $u_1(t), u_2(t), u_3(t), u_4(t)$ from the steady state

i.e. $N_i(t) = \bar{N}_i + u_i(t),\ i = 1,2,3,4$ --------- (4.3)

Substituting (4.1) in (2.1), (2.2), (2.3), (2.4) and neglecting products and higher powers of u_1, u_2, u_3, u_4.

We get

$$\frac{du_1}{dt} = -a_{11}\bar{N}_1 u_1 - a_{12}\bar{N}_1 u_2 + a_{13}\bar{N}_1 u_3 \quad \text{--------- (4.4)}$$

$$\frac{du_2}{dt} = -a_{22}\bar{N}_2 u_2 + a_{21}\bar{N}_2 u_1 + a_{24}\bar{N}_2 u_4 \quad \text{--------- (4.5)}$$

$$\frac{du_3}{dt} = -a_{33}\bar{N}_3 u_3 \quad \text{--------- (4.6)}$$

$$\frac{du_4}{dt} = -a_{44}\bar{N}_4 u_4 \quad \text{--------- (4.7)}$$

The characteristic equation of which is

$$\left(\lambda^2 + A\lambda + B\right)\left(\lambda + a_{33}\bar{N}_3\right)\left(\lambda + a_{44}\bar{N}_4\right) = 0 \quad \text{--------- (4.8)}$$

where $A = a_{11}\bar{N}_1 + a_{22}\bar{N}_2$ and $B = \left(a_{11}a_{22} - a_{12}a_{21}\right)\bar{N}_1\bar{N}_2$ --------- (4.9)

Two of the four roots are $-a_{33}\bar{N}_3$ and $-a_{44}\bar{N}_4$ are negative

The other roots λ_1, λ_2 satisfy the equation $\left(\lambda^2 + A\lambda + B\right) = 0$.--------- (4.10)

Case (A):

If both the roots λ_1 and λ_2 are negative

Hence the co-existent state is **stable.**

The trajectories are given by

$$u_1 = \left[\frac{a_{12}\bar{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_2 + a_{11}\bar{N}_1\right)}{\lambda_2 - \lambda_1}\right]e^{\lambda_1 t} + \left[\frac{a_{12}\bar{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_1 + a_{11}\bar{N}_1\right)}{\lambda_1 - \lambda_2}\right]e^{\lambda_2 t} + \gamma_1 e^{-a_{33}\bar{N}_3 t} + \gamma_2 e^{-a_{44}\bar{N}_4 t} \quad \text{--------- (4.11)}$$

$$u_2 = \left[\frac{a_{12}\bar{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_2 + a_{11}\bar{N}_1\right)}{\lambda_1 - \lambda_2}\right]\alpha e^{\lambda_1 t} + \left[\frac{a_{12}\bar{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_1 + a_{11}\bar{N}_1\right)}{\lambda_2 - \lambda_1}\right]\beta e^{\lambda_2 t} + \gamma_3 e^{-a_{33}\bar{N}_3 t} + \gamma_4 e^{-a_{44}\bar{N}_4 t} \quad \text{--------- (4.12)}$$

$u_3 = u_{30}e^{-a_{33}\bar{N}_3 t}$ --------- (4.13) $u_4 = u_{40}e^{-a_{44}\bar{N}_4 t}$ --------- (4.14)

Here $\mu_1 = \gamma_1 - \gamma_2$; $\mu_2 = \frac{a_{44}\bar{N}_4\gamma_2}{a_{12}\bar{N}_1} + \frac{\gamma_1 a_{11}}{a_{12}} - \frac{a_{13}u_{30}}{a_{12}} - \frac{a_{33}\bar{N}_3\gamma_1}{a_{12}\bar{N}_1} - \frac{a_{11}\gamma_2}{a_{12}}$ ----(4.15)

$$\gamma_1 = \frac{\alpha_2}{a_{33}^2\bar{N}_3{}^2 - \left(a_{11}\bar{N}_1 + a_{22}\bar{N}_2\right)a_{33}\bar{N}_3 + \alpha_1} \qquad \text{------- (4.16)}$$

$$\gamma_2 = \frac{\alpha_3}{a_{44}\bar{N}_4{}^2 - \left(a_{11}\bar{N}_1 + a_{22}\bar{N}_2\right)a_{44}\bar{N}_4 + \alpha_1}\ ;\ \alpha_1 = a_{11}a_{22}\bar{N}_1\bar{N}_2 + a_{12}a_{21}\bar{N}_1\bar{N}_2 \qquad \text{------- (4.17)}$$

$$\alpha_2 = a_{13}\bar{N}_1 u_{30}\left(a_{22}\bar{N}_2 - a_{33}\bar{N}_3\right) \quad ; \quad \alpha_3 = a_{12}a_{24}u_{40}\bar{N}_1\bar{N}_2 \qquad \text{------- (4.18)}$$

$$\alpha = \frac{\lambda_1}{a_{12}\bar{N}_1} + \frac{a_{11}}{a_{12}} \quad ; \quad \beta = \frac{\lambda_2}{a_{12}\bar{N}_1} + \frac{a_{11}}{a_{12}} \qquad \text{------- (4.19)}$$

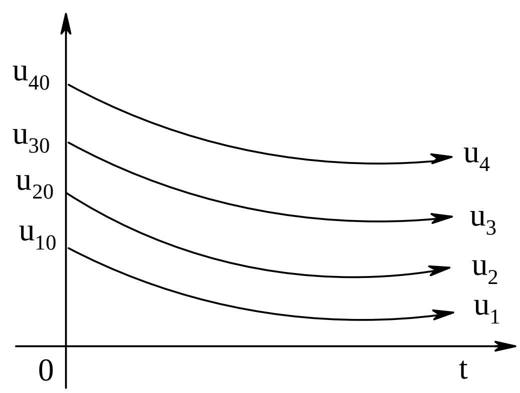
$$\gamma_3 = \frac{a_{13}u_{30}}{a_{12}} + \left(\frac{a_{33}\bar{N}_3}{\bar{N}_1} - a_{11}\right)\frac{\gamma_1}{a_{12}} \quad ; \quad \gamma_4 = \left(a_{11} - \frac{a_{44}\bar{N}_4}{\bar{N}_1}\right)\frac{\gamma_2}{a_{12}} \qquad \text{------- (4.20)}$$

and $u_{10}, u_{20}, u_{30}, u_{40}$ are the initial values of u_1, u_2, u_3, u_4 respectively.

There would arise in all 576 cases depending upon the ordering of the magnitudes of the growth rates a_1, a_2, a_3, a_4 and the initial values of the perturbations $u_{10}(t), u_{20}(t), u_{30}(t), u_{40}(t)$ of the species S_1, S_2, S_3, S_4. Of these 576 situations some typical variations are illustrated through respective solution curves that would facilitate to make some reasonable observations.

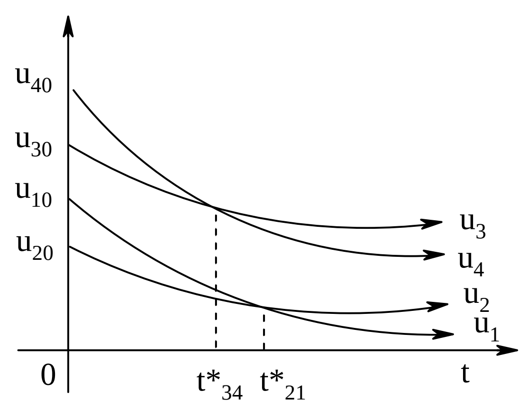
Case (i): If $u_{10} < u_{20} < u_{30} < u_{40}$ and $a_1 < a_2 < a_3 < a_4$

In this case the Prey (S_1) has the least natural birth rate and the Host (S_4) of S_2 dominates the Host (S_3) of S_1, Predator (S_2), Prey (S_1) in natural growth rate as well as in its population strength. And u_1, u_2, u_3, u_4 are converging asymptotically to the equilibrium point. Hence the equilibrium point is **stable**.



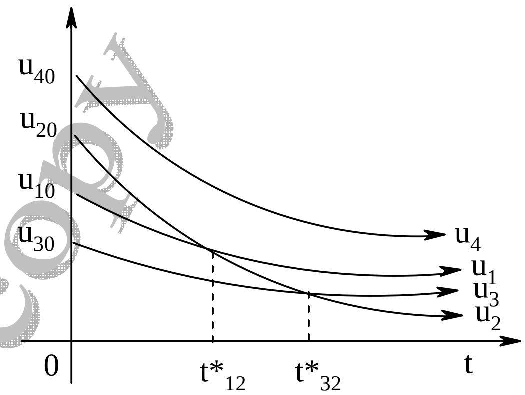
Case (ii): If $u_{20} < u_{10} < u_{30} < u_{40}$ and $a_1 < a_2 < a_4 < a_3$

In this case the Prey (S_1) has the least natural birth rate. Initially it is dominated over by the Predator (S_2) till the time instant t^*_{21} and there after the dominance is reversed. Also the Host (S_4) of S_2 dominates over the Host (S_3) of S_1 till the time instant t^*_{34} and the dominance gets reversed there after.



Case (iii): If $u_{30} < u_{10} < u_{20} < u_{40}$ and $a_2 < a_3 < a_1 < a_4$

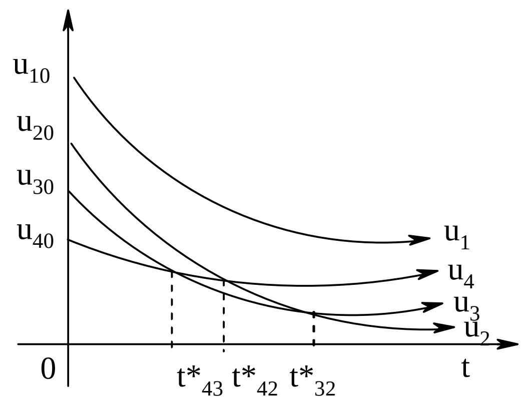
In this case the Predator (S_2) has the least natural birth rate. Initially it is dominated over by the Host (S_3) of S_1, Prey (S_1) till the time instant t^*_{32}, t^*_{12} respectively and there after the dominance is reversed.



Case (iv): If $u_{40} < u_{30} < u_{20} < u_{10}$ and $a_2 < a_3 < a_4 < a_1$

In this case the Predator (S_2) has the least natural birth rate. Initially it is dominated over by the Host (S_3) of S_1, Host (S_4) of S_2 till the time instant t^*_{32}, t^*_{42} respectively and there after the dominance is reversed.

Also the Host (S_3) of S_1 dominated over the Host (S_4) of S_2 till the time instant t^*_{43} and the dominance gets reversed there after.



Case (B):

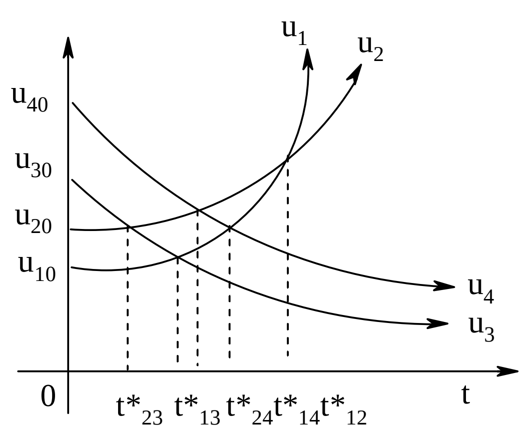
If one root (λ_1) is negative while the other root (λ_2) is positive

Hence the co-existent state is **unstable.**

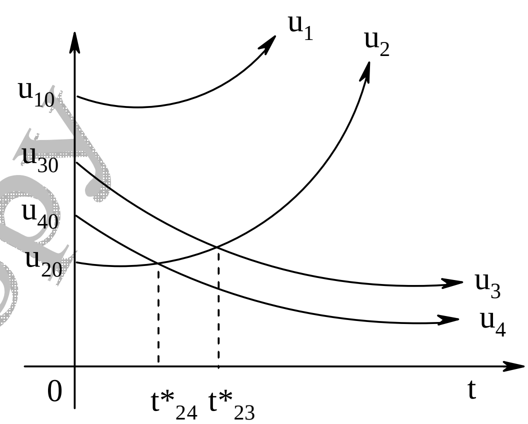
The trajectories in this case are same as in Case (A).

Case (i): If $u_{10} < u_{20} < u_{30} < u_{40}$ and $a_3 < a_2 < a_4 < a_1$

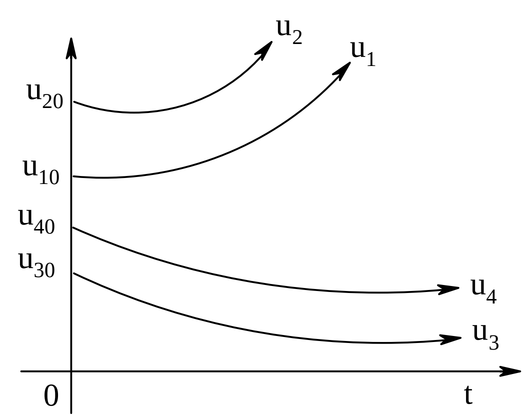
In this case the Host (S_3) of S_1 has the least natural birth rate. Initially it is dominated over by the Prey (S_1), the Predator (S_2) till the time instant t^*_{13}, t^*_{23} respectively and there after the dominance is reversed. Also the Host (S_4) of S_2 dominates over the Prey (S_1), the Predator (S_2) till the time instant t^*_{14}, t^*_{24} respectively and there after the dominance is reversed. Similarly the Predator (S_2) dominates over the Prey (S_1) till the time instant t^*_{12} and the dominance gets reversed there after.



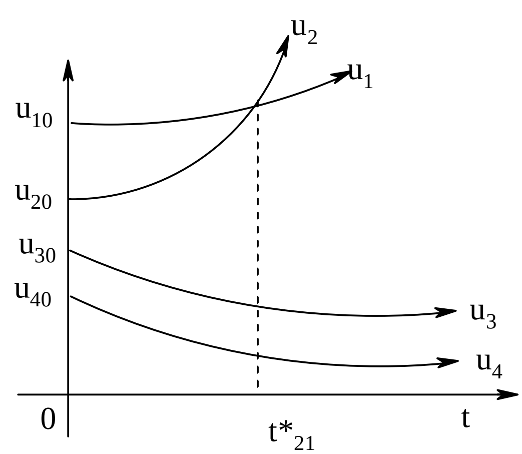
Case (ii): If $u_{20} < u_{40} < u_{30} < u_{10}$ and $a_4 < a_3 < a_2 < a_1$
In this case the Host (S_4) of S_2 has the least natural birth rate. Initially it is dominated over by the Predator (S_2) till the time instant t^*_{24} and there after the dominance is reversed. Also the Host (S_3) of S_1 dominates over the Predator (S_2) till the time instant t^*_{23} and the dominance gets reversed there after.



Case (iii): If $u_{30} < u_{40} < u_{10} < u_{20}$ and $a_1 < a_3 < a_2 < a_4$
In this case the Host (S_3) of S_1 has the least natural birth rate and the Predator (S_2) dominates the Prey (S_1), Host (S_4) of S_2, Host (S_3) of S_1 in natural growth rate as well as in its population strength.



Case (iv): If $u_{40} < u_{30} < u_{20} < u_{10}$ and $a_4 < a_3 < a_1 < a_2$
In this case the Host (S_4) of S_2 has the least natural birth rate. Initially the Prey (S1) dominates over the Predator (S2) till the time instant t^*_{21} and there after the dominance is reversed.



4.1 Trajectories of perturbations :

The trajectories in the $u_3 - u_4$ plane given by

$$\left(\frac{u_3}{u_{30}}\right)^{a_4} = \left(\frac{u_4}{u_{40}}\right)^{a_3} \qquad \text{------- (4.1.1)}$$

and are shown in Fig. 2.

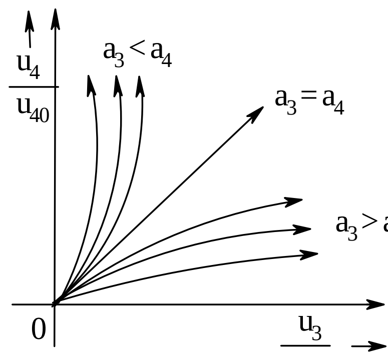


Fig. 2

And the trajectories in the $u_1 - u_3$, $u_1 - u_4$, $u_2 - u_3$, $u_2 - u_4$ planes are

$$x = A_1\, y^{\frac{-\lambda_1}{a_3}} + B_1\, y^{\frac{-\lambda_2}{a_3}} + \overline{\gamma}_1\, y + \overline{\gamma}_2\, y^{\frac{a_4}{a_3}},\; x = A_1\, z^{\frac{-\lambda_1}{a_4}} + B_1\, z^{\frac{-\lambda_2}{a_4}} + \overline{\gamma}_1\, z^{\frac{a_3}{a_4}} + \overline{\gamma}_2\, z, \quad \text{----- (4.1.2)}$$

$$x_1 = A_2\, y^{\frac{-\lambda_1}{a_3}} + B_2\, y^{\frac{-\lambda_2}{a_3}} + \overline{\gamma}_3\, y + \overline{\gamma}_4\, y^{\frac{a_4}{a_3}},\; x_1 = A_2\, z^{\frac{-\lambda_1}{a_4}} + B_2\, z^{\frac{-\lambda_2}{a_4}} + \overline{\gamma}_3\, z^{\frac{a_3}{a_4}} + \overline{\gamma}_4\, z \quad \text{---- (4.1.3)}$$

respectively

where $$x = \frac{u_1}{u_{10}},\; x_1 = \frac{u_2}{u_{20}},\; y = \frac{u_3}{u_{30}},\; z = \frac{u_4}{u_{40}} \quad \text{------- (4.1.4)}$$

and $$A_1 = \frac{a_{12}\overline{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_2 + a_{11}\overline{N}_1\right)}{u_{10}\left(\lambda_2 - \lambda_1\right)} \quad \text{------- (4.1.5)}$$

$$B_1 = \frac{a_{12}\overline{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_1 + a_{11}\overline{N}_1\right)}{u_{10}\left(\lambda_1 - \lambda_2\right)} \quad \text{------- (4.1.6)}$$

$$A_2 = \left[\frac{a_{12}\overline{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_2 + a_{11}\overline{N}_1\right)}{u_{20}\left(\lambda_1 - \lambda_2\right)}\right]\alpha \quad \text{------- (4.1.7)}$$

$$B_2 = \left[\frac{a_{12}\overline{N}_1\left(\mu_2 + u_{20}\right) - \left(\mu_1 - u_{10}\right)\left(\lambda_1 + a_{11}\overline{N}_1\right)}{u_{20}\left(\lambda_2 - \lambda_1\right)}\right]\beta \quad \text{------- (4.1.8)}$$

$$\overline{\gamma}_1 = \frac{\gamma_1}{u_{10}},\; \overline{\gamma}_2 = \frac{\gamma_2}{u_{10}},\; \overline{\gamma}_3 = \frac{\gamma_3}{u_{20}},\; \overline{\gamma}_4 = \frac{\gamma_4}{u_{20}} \quad \text{------- (4.1.9)}$$

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